# Entropy of Coupled Map Lattices 

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#### Abstract

The entropy of coupled map lattices with respect to the group of space-time translations is considered. We use the notion of generalized Lyapunov spectra to prove the analogue of the Ruelle inequality and the Pesin formula.


KEY WORDS: Coupled map lattice; Pesin formula; Ruelle inequality; SBR measure.

## 1. INTRODUCTION

The behavior of finite-dimensional hyperbolic diffeomorphisms is one of the best-developed branches of dynamical systems theory. Therefore the natural question arises as to which features of this behavior persist in the infinite-dimensional setting.

The simplest example to begin with is coupled map lattices. Here the configuration space $\mathbf{X}$ is the product of the countable number of copies of finite-dimensional manifolds $\mathbf{X}=\prod_{i} X_{i}$. In this paper the index $i$ runs over integers ("one-dimensional lattice"). The map $\Phi$ is a perturbation of the product of "uncoupled" diffeomorphisms $(\mathbf{f}(\mathbf{x}))_{i}=f\left(\mathbf{x}_{i}\right)$ due to an interaction $J$ which is translation invariant and rapidly decreasing in space. The last assumption can be formalized mathematically in many different ways. The simplest possibility is to require that $f$ is a hyperbolic map and $J$ is so small that methods of stability theory can be applied. Under these conditions it was shown in refs. 1 and 5 that the basic results of the finite-dimensional theory such as the stable-manifold theorem, the construction of Markov partitions, and the existence of SBR measure remain valid. The purpose of this paper is to generalize the entropy formulas.

[^0]Let us recall that the classical Pesin formula states that in the ergodic case the measure-theoretic entropy is equal to the sum of positive Lyapunov exponents. It is based on the Oseledeĉ theorem. So the first problem is to obtain the counterpart to this theorem. The simplest proof of Oseledê theorem ${ }^{(6)}$ proceeds as follows. Let $\lambda_{1}^{(m)}(x) \geqslant \lambda_{2}^{(m)}(x) \geqslant \cdots \geqslant$ $\lambda_{n}^{(m)}(x)$ be the eigenvalues of $\left[\left(d \Phi^{m}(x)\right)^{*}\left(d \Phi^{m}(x)\right)\right]^{1 / 2}$. Consider $s_{j}^{m \prime}(x)=$ $\sum_{k=1}^{j} \ln \lambda_{k}^{(m)}(x)$. The existence of the limit $\lim _{m \rightarrow \alpha}(1 / m) s_{j}^{(m)}$ follows by the subadditive ergodic theorem since one can interpret exp $s_{j}^{(m)}$ as the largest eigenvalue of $d \Phi^{m}$ acting on $j$-forms. This approach succeeds also in infinite dimensions if $d \Phi$ is a compact operator. ${ }^{(3,9)}$ In our situation the last assumption is never valid because of the translation invariance. However, a natural generalization arises if we want to compute the entropy with respect to the group of the space-time translations, that is, the "measuretheoretic entropy of the time shift per degree of freedom" rather then just the measure-theoretic entropy of the time shift. In this case we should average by the number of degrees of freedom $N$ and perform the limit as $N$ tend to infinity before applying the traditional arguments. This program was partly carried out in ref. 12 for another dynamical system: the hardcore gas in an infinite vessel. The above-mentioned approach to the Oseledeĉ theorem seems to be more natural than doing time averaging before the space averaging because while our system can be considered as a small perturbation of a finite-dimensional one for any fixed moment of time, the time average limit depends essentially on the whole infinitedimensional space.

The important difference from the finite-dimensional case is that the generalized Lyapunov spectrum so obtained does not correspond to any invariant splitting of the tangent bundle, not to mention foliations. So its dynamical importance is not clear. However, in this paper we show that the counterparts to both the Ruelle inequality and the Pesin formula hold if the ordinary Lyapunov spectrum is replaced by the generalized one.

The structure of the paper is the following. Section 2 contains the precise assumptions about the interaction $J$. In Section 3 we define the expansion rate, which is the mean value of the sum of positive Lyapunov exponents. The existence of the limiting quantity is demonstrated in Section 4. Our arguments here are similar to those of ref. 11. After the existence is established, the Ruelle inequality follows by exactly the same arguments as in Ruelle's original paper. ${ }^{(7)}$ This is discussed in Section 5. In Section 6 we recall the construction of the SBR measure for coupled map lattices given in ref. 5. The Pesin formula is proven in Section 7. The reason why it holds is that in the hyperbolic case the convergence in the Pesin formula for finite-dimensional system whose limit is our coupled map lattice is uniform in the number of degrees of freedom. The proof of the Pesin formula gives
an affirmative answer to a general question posed in ref. 11 for our very special case.

Since it is interesting to find the weakest possible conditions under which this theory holds, we do not impose any hyperbolicity conditions in Sections $2-5$. Of course this paper is only the first step toward understanding the entropy properties of differential infinite-dimensional systems.

## 2. COUPLED MAP LATTICES

Here we define the system with which we deal. ${ }^{(5)}$ Let $X$ be a compact Riemann manifold. Choose a countable number of copies $X_{i}$ of $X$ and set $\mathbf{X}=\prod_{i=-\infty}^{+\infty} X_{i}, \quad X_{N_{1}, N_{2}}=\prod_{i=N_{1}}^{N_{2}} X_{i}, \quad X_{N}=X_{-N . N}$. Elements of $\mathbf{X}$ are denoted by $\mathbf{x}=\left\{\mathbf{x}_{i}\right\}_{i=-\infty}^{+\infty}$ and elements of $X_{N}$ by $x^{(N)}$. We write $S$ for the space shift $(S(\mathbf{x}))_{i}=\mathbf{x}_{i+1}$. Denote by $p_{N_{1}, N_{2}}, p_{N}$ and $Q_{N}$ the natural projections $p_{N_{1}, N_{2}}: \mathbf{X} \rightarrow X_{N_{1}, N_{2}}, p_{N}: \mathbf{X} \rightarrow X_{N}$ and $Q_{N}: X_{N} \rightarrow X_{N-1}$. The distances on $\mathbf{X}$ and $X_{N_{t}, N_{2}}$ are given by $d(x, y)=\sup _{i} \rho\left(x_{i}, y_{i}\right)$, where $\rho$ is the distance on $X$. We write $V_{i}(x)=T_{x_{i}}\left(X_{i}\right)$. The tangent space $V(\mathbf{x})=T_{\mathbf{x}} \mathbf{X}$ may be identified with $\oplus_{i} V_{i}\left(\mathbf{x}_{i}\right)$, with $\|v\|=\sup _{i}\left\|v_{i}\right\|$. We set

$$
V^{N_{1}, N_{2}}(\mathbf{x})=\bigoplus_{i=N_{1}}^{N_{2}} V_{i}(\mathbf{x}), \quad V^{N}(\mathbf{x})=V^{0, N-1}
$$

(note, however, that $X_{N}=X_{-N . N}$ ) and $P_{N_{1}, N_{2}}$ and $P_{N}$ are the corresponding projections. We also consider the space $H(\mathbf{x})$ of vectors with a finite $l_{2}$-norm $\|v\|_{2}=\left(\sum_{i}\|v\|^{2}\right)^{1 / 2}$.

Now we define our map. Let $f$ be a diffeomorphism of $X$ and $\mathbf{f}$ be the diffeomorphism of $\mathbf{X}$ given by $(\mathbf{f}(\mathbf{x}))_{i}=f\left(\mathbf{x}_{i}\right)$. We study diffeomorphisms of the form $\Phi=J \circ f$, where $J$ is an interaction map defined below. Let $J_{0}$ be a map $J_{10}: \mathbf{X} \rightarrow X$ such that there exist constants $K_{1}$ and $\kappa_{1}<1$ and mappings $J_{0}^{(N)}: X_{N} \rightarrow X$ such that

$$
\begin{align*}
d_{C_{2}}\left(J_{0}^{(N)}, J_{0}^{(N-1)} Q_{N}\right) & \leqslant K_{1} \kappa_{1}^{N}  \tag{1}\\
d_{C_{2}}\left(J_{0}, J_{0}^{(N)} p_{N}\right) & \leqslant K_{1} \kappa_{1}^{N} \tag{2}
\end{align*}
$$

A $\left(K_{1}, \kappa_{1}\right)$ interaction is given by $(J(\mathbf{x}))_{i}=S^{i} J_{0} S^{-i}(\mathbf{x})$. Since $J$ is $S$-invariant, $\Phi S=S \Phi$. More general interactions can be considered as long as they satisfy conditions (3), (4) below. Let $D_{n \prime \prime}^{\prime \prime \prime}(\mathbf{x})$ be the diágonal part of $d \Phi^{\prime \prime \prime}$, that is, $D_{n}^{\prime \prime \prime} v=P_{i-n . i+n} d \Phi^{\prime \prime \prime} v$ if $v \in V_{i}(\mathbf{x})$. Clearly (1) and (2) imply

$$
\begin{equation*}
d \Phi: H(\mathbf{x}) \rightarrow H(\Phi \mathbf{x}) \quad \text { and } \quad\|d \Phi\|_{2} \leqslant K_{2} \tag{3}
\end{equation*}
$$

[where $\left.K_{2}=K_{1} /\left(1-\kappa_{1}\right)\right]$ and given $\varepsilon, m$ there exists $n_{0}=n_{0}(m)$ such that for all $n \geqslant n_{0}$

$$
\begin{equation*}
\left\|D_{n}^{\prime \prime \prime}(\mathbf{x})-d \Phi^{\prime \prime \prime}(\mathbf{x})\right\|_{2} \leqslant \varepsilon \tag{4}
\end{equation*}
$$

Conditions (3) and (4) guarantee the existence of the expansion rate proven in Section 4.

## 3. EXPANSION RATE

In order to define the expansion rate we need some extra notations. If $E$ and $F$ are Hilbert spaces and $A: E \rightarrow F$ is a linear operator, we set $|A|=\sqrt{A^{*} A}$. In case $E$ is finite-dimensional we denote by $\lambda_{1}(A) \geqslant$ $\lambda_{2}(A) \geqslant \cdots \geqslant \lambda_{n}(A)$ the eigenvalues of $|A|: E \rightarrow E$ and $\operatorname{det} A$ is the determinant of $|A|$. We call $v(A)$ the normalized counting measure of the eigenvalues $v(A)=(1 / \operatorname{dim} E) \sum_{j} \delta_{i_{j}(A)}$. The expansion rate of $A$ can be defined as follows:

$$
R(A)=\sum_{\text {j, }|A|>1} \ln \lambda_{j}(A)=\operatorname{dim} E \int \ln ^{+}(t) d v(A)(t)
$$

where $\ln ^{+} t=\max (0, \ln t)$. Usually we consider the restriction of $A$ to some finite-dimensional subspace $\bar{E} \subset E$. To avoid long subscripts we write $\lambda_{j}(A \mid \bar{E}), \operatorname{det}(A \mid \bar{E}), \ldots$ instead of $\lambda_{j}\left(\left.A\right|_{\bar{E}}\right), \operatorname{det}\left(\left.A\right|_{\bar{E}}\right), \ldots$. For example,

$$
\begin{equation*}
R(A)=\max _{\bar{E} \in E} \ln \operatorname{det}(A \mid \bar{E}) \tag{5}
\end{equation*}
$$

Now we collect for future use some elementary properties of $v(A)$ and $R(A)$. The proofs are based on the observation that the inequality

$$
v(A)([t, \infty]) \geqslant \frac{N}{\operatorname{dim} E} \quad\left\{v(A)([0, t]) \geqslant \frac{N}{\operatorname{dim} E}\right\}
$$

is equivalent to the existence of the subspace $\bar{E}$ of the dimension $N$ on which ( $A e, A e) \geqslant t^{2}(e, e)\left[(A e, A e) \leqslant t^{2}(e, e)\right.$ respectively $]$.

Proposition 1. Let $\|A\| \leqslant a$; then:
(1) If $\|B\| \leqslant \varepsilon<a$, then

$$
\begin{aligned}
v(A)\left(\left[\sqrt{t_{1}+3 \varepsilon a}, \sqrt{t_{2}-3 \varepsilon a}\right]\right) & \leqslant v(A+B)\left(\left[t_{1}, t_{2}\right]\right) \\
& \leqslant v(A)\left(\left[\sqrt{t_{1}-3 \varepsilon a}, \sqrt{t_{2}+3 \varepsilon a}\right]\right)
\end{aligned}
$$

(2) If $\bar{E} \subset E$, codim $\bar{E}=n$, then

$$
\left\lvert\, v(A)([t, \infty])-v(A \mid \bar{E})\left([t, \infty) \left\lvert\, \leqslant \frac{2 n}{\operatorname{dim} \bar{E}}\right.\right.\right.
$$

(3) If $E=E_{1} \oplus E_{2}, A(E)=A\left(E_{1}\right) \oplus A\left(E_{2}\right)$, then

$$
v(A)=\frac{\operatorname{dim} E_{1}}{\operatorname{dim} E} v\left(A \mid E_{1}\right)+\frac{\operatorname{dim} E_{2}}{\operatorname{dim} E} v\left(A \mid E_{2}\right)
$$

(4) If $(\cdot, \cdot)_{E}^{\prime}$ and $(\cdot, \cdot)_{F}^{\prime}$ are other scalar products on $E$ and $F$, respectively, such that $(1 / \alpha)\|\cdot\|_{(\cdot)} \leqslant\|\cdot\|_{(\cdot)} \leqslant \alpha\|\cdot\|_{(\cdot)}$, then

$$
v(A)\left(\left[\alpha t_{1}, \frac{t_{2}}{\alpha}\right] \leqslant v^{\prime} A\right)\left(\left[t_{1}, t_{2}\right]\right) \leqslant v(A)\left(\left[\frac{t_{1}}{\alpha}, \alpha t_{2}\right]\right)
$$

where in $v^{\prime}(A), A^{*}$ and $|A|$ are calculated using $(\cdot, \cdot)^{\prime}$ instead of $(\cdot, \cdot)$.
Corollary 1. There exists a constant $C_{1}$ such that:
(1) If $\|B\| \leqslant \varepsilon \leqslant\|A\|$, then

$$
|R(A+B)-R(A)| \leqslant C_{1} \sqrt{\varepsilon\|A\|} \operatorname{dim} E
$$

(2) We have

$$
\left|R\left(A \mid E_{1}\right)-R\left(A \mid E_{2}\right)\right| \leqslant C_{1}\left(\operatorname{dim}\left(E_{1}+E_{2}\right)-\operatorname{dim}\left(E_{1} \cap E_{2}\right)\right)\|A\|
$$

(3) If $E=E_{1} \oplus E_{2}, A(E)=A\left(E_{1}\right) \oplus A\left(E_{2}\right)$, then $R(A)=R\left(A \mid E_{1}\right)+$ $R\left(A \mid E_{2}\right)$.
(4) If $(\cdot, \cdot)_{E, F}^{\prime}$ are other scalar products on $E$ and $F$ respectively, such that $(1 / \alpha)|\cdot|_{(.)} \leqslant\|\cdot\|_{(\cdot)} \leqslant \alpha\|\cdot\|_{(\cdot)}$, then

$$
\left|R(A)-R^{\prime}(A)\right| \leqslant C_{1} \ln \alpha \operatorname{dim} E
$$

where in $R^{\prime}(A), A^{*}$ and $|A|$ are calculated using $(\cdot, \cdot)^{\prime}$ instead of $(\cdot, \cdot)$.
Now we are in position to define the expansion rate of $\Phi$. Set

$$
\begin{aligned}
R(\mathbf{x}, m, N) & =R\left(d \Phi^{m}(\mathbf{x}) \mid V^{N}(\mathbf{x})\right) \\
R_{n}(\mathbf{x}, m, N) & =R\left(D_{n}^{\prime \prime \prime}(\mathbf{x}) \mid V^{N}(\mathbf{x})\right) \\
v(\mathbf{x}, m, N) & =v\left(d \Phi^{m}(\mathbf{x}) \mid V^{N}(\mathbf{x})\right) \\
v_{n}(\mathbf{x}, m, N) & =v\left(D_{n}^{\prime \prime \prime}(\mathbf{x}) \mid V^{N}(\mathbf{x})\right)
\end{aligned}
$$

By the expansion rate of $\Phi$ we mean the limit

$$
R(\mathbf{x})=\lim _{m \rightarrow \infty} \lim _{N \rightarrow \infty} \frac{1}{m N} R(\mathbf{x}, m, N)
$$

The existence of this limit is proven in the next section.

## 4. EXISTENCE OF THE EXPANSION RATE

Theorem 1. Let $\mu$ be an $S$-invariant measure, then the limit

$$
R(\mathbf{x}, m)=\lim _{N \rightarrow \infty} \frac{R(\mathbf{x}, m, N)}{N}
$$

exists almost surely and

$$
\int R(\mathbf{x}, m) d \mu(\mathbf{x})=\lim _{N \rightarrow \infty} \int \frac{R(\mathbf{x}, m, N)}{N} d \mu(\mathbf{x})
$$

If $\mu$ is $S$-ergodic, then $R(x, m)$ is constant almost surely.
This statement is the immediate corollary of the following result.
Lemma 1. The limit $v(\mathbf{x}, m)=\lim _{N \rightarrow \propto} v(\mathbf{x}, m, N)$ exists almost surely.

Proof. Take $\phi \in C\left[0, K_{2}^{m}\right]$. By the Proposition 1.1, given $\varepsilon$, we can find a large $n_{0}$ such that the inequality

$$
\left|\int \phi(t) d v(\mathbf{x}, m, N)(t)-\int \phi(t) d v_{n}(\mathbf{x}, m, N)(t)\right| \leqslant \varepsilon
$$

holds for $n \leqslant n_{0}$. So, it is enough to prove the existence of the limit of $v_{n}(\mathbf{x}, m, N)$ for all $n$. By Proposition 1.2,

$$
\begin{aligned}
& \left|\int \phi(t) d v_{n}\left(\mathbf{x}, m, N_{1}+N_{2}\right)-\int \phi(t) d v\left(D_{n}^{m \prime \prime} \mid V^{N_{1}-n}(\mathbf{x}) \oplus V^{N_{1}+n \cdot N_{1}+N_{2}}(\mathbf{x})\right)(t)\right| \\
& \quad \leqslant \frac{2 n\|\phi\|}{N_{1}+N_{2}-2 n}
\end{aligned}
$$

Let $f_{N}(\mathbf{x})=N \int \phi(t) d v_{n}(\mathbf{x}, m, N)(t)$; then the last inequality and Proposition 1.3 imply

$$
\left|f_{N_{1}+N_{2}}(\mathbf{x})-f_{N_{1}}(\mathbf{x})-f_{N_{2}}\left(S^{N_{1}} \mathbf{x}\right)\right| \leqslant \operatorname{Const}(n)
$$

so the statement of the lemma follows from the subadditive ergodic theorem applied to the sequences $f_{N}(\mathbf{x}) \mp \operatorname{Const}(n)$.

The next step is to show that the $R(\mathbf{x}, m)$ form a subadditive sequence.
Lemma 2. $R\left(\mathbf{x}, m_{l}+m_{2}\right) \leqslant R\left(\mathbf{x}, m_{1}\right)+R\left(\Phi^{m_{2}} \mathbf{x}, m_{2}\right)$.
Proof. Again it is enough to replace $d \Phi^{m_{i}}$ by $D_{n}^{m_{i}}$ and $d \Phi^{m_{1}+m_{2}}(\mathbf{x})$ by $D_{n}^{m 2}\left(\Phi^{m \prime \prime}(\mathbf{x})\right) D_{n}^{m \prime \prime}(\mathbf{x})$. But in view of (5)

$$
R\left(D_{n}^{m_{2}}\left(\Phi^{m_{1}}(\mathbf{x})\right) D_{n}^{m_{1}}(\mathbf{x}) \mid V^{N}(\mathbf{x})\right) \leqslant R_{n}\left(\mathbf{x}, m_{1}, N\right)+R_{n}\left(\Phi^{m_{1}}(\mathbf{x}), m_{2}, N+n\right)
$$

and the lemma follows by Corollary 1.2.
The application of the subadditive ergodic theorem yields the following result.

Theorem 2. If $\mu$ is also $\Phi$-invariant, then the limit

$$
R(\mathbf{x})=\lim _{m \rightarrow \infty_{i}} \frac{R(\mathbf{x}, m)}{m}
$$

exists almost surely and

$$
\int R(\mathbf{x}) d \mu(\mathbf{x})=\lim _{m \rightarrow \infty} \int \frac{R(\mathbf{x}, m)}{m} d \mu(\mathbf{x})
$$

If $\mu$ is ( $S, \Phi$ )-ergodic, then $R(\mathbf{x})$ is constant almost surely.
Remark. Set

$$
r(\mathbf{x}, c, m, N)=\ln \max _{E \subset w_{(\mathbf{x})} \operatorname{dim} E=c N} \operatorname{det}\left(d \Phi^{\prime \prime \prime}(\mathbf{x}) \mid E\right)
$$

By the same subadditivity arguments it is possible to prove the existence of the limits

$$
r(\mathbf{x}, c, m)=\lim _{N \rightarrow \infty} \frac{r(\mathbf{x}, c, m, N)}{N}, \quad r(\mathbf{x}, c)=\lim _{m \rightarrow \infty} \frac{r(\mathbf{x}, c, m)}{m}
$$

The calculation of $r(\mathbf{x}, c, m, N)$ can be done using the following observation. Let $A_{m . N}^{\wedge k}(\mathbf{x})$ be the $k$ th exterior power of $d \Phi^{\prime \prime \prime}(\mathbf{x}) \mid V^{N}(\mathbf{x})$; then $(\mathbf{x}, c, m, N)=\ln \lambda_{1}\left(A_{m . N}^{\wedge c N}(\mathbf{x})\right)$ and therefore

$$
\ln \operatorname{Tr}\left(A_{m . N}^{\wedge c N}(\mathbf{x})\right)-N \operatorname{dim} X \ln 2 \leqslant r(\mathbf{x}, c, m, N) \leqslant \ln \operatorname{Tr}\left(A_{m . N}^{\wedge c N}(\mathbf{x})\right)
$$

so $\left[\ln \operatorname{Tr}\left(A_{m, N}^{\wedge}(\mathbf{x})\right)\right] / m N$ is a good approximation to $r(\mathbf{x}, c, m, N) / m N$ if $m$ is large enough (cf. ref. 11 and the discussion in the introduction). $R(\mathbf{x})$ can be expressed in terms of $r(\mathbf{x}, c)$ as follows: $R(\mathbf{x})=\sup _{c} r(\mathbf{x}, c)$.

## 5. RUELLE INEQUALITY

In this section we prove an infinite-dimensional counterpart of the Ruelle inequality. ${ }^{(7)}$

Theorem 3. If $\mu$ is an $(S, \Phi)$-invariant measure, then $h(\mu) \leqslant \int R(\mathbf{x})$ $d \mu(\mathbf{x})$.

Proof. This statement can be proven by exactly the same arguments as in ref. 7. Let $T$ be a triangulation of $X_{0}$ and $T_{k}$ be a $k$-fold barycentric subdivision of $T$. Since

is the Borel $\sigma$-algebra of $\mathbf{X}$, we have $h_{S, \phi}(\mu)=\lim _{k \rightarrow \infty} h_{S . \phi}\left(T_{k}, \mu\right)$. The last expression can be bounded by $\lim _{N \rightarrow \infty} h\left(T_{k, N} \mid \Phi^{-1} T_{k, N}\right)$, where $T_{k, N}=\vee_{j=\ldots N}^{N} S^{j} T_{k}$. Denote by $C_{T_{h . N}}(\mathbf{x})$ the element of $T_{k . N}$ containing $\mathbf{x}$ and let $\Gamma(k, N, \mathbf{x})$ be the number of elements $C_{T_{k, N}}^{j}$ of $T_{k, N}$ such that $C_{T_{k, s}}^{j} \cap \Phi C_{T_{k, N}}(\mathbf{x}) \neq \varnothing$; then

$$
h\left(t_{k . N} \mid \Phi^{-1} T_{k . N}\right) \leqslant \int \ln \Gamma(k, N, \mathbf{x}) d \mu(\mathbf{x})
$$

Let $d_{k}$ be the diameter of $T_{k}$. We can find constants $n_{k}, \alpha_{k}, \beta_{k}$ such that $X_{-\left(N+n_{k}\right)-N} \times X_{N . N+n_{k}}$ can be covered by $\left(1 / \alpha_{k}\right)^{m_{k}}$ balls $B_{l}^{N}$ of radius $\beta_{k}$ such that if $\mathbf{x}_{i}^{\prime}=\mathbf{x}_{i}^{\prime \prime}$ for $|i| \leqslant N$ and $\left(p_{-\left(N+m_{k}\right),-N} \mathbf{x}^{\prime}, p_{N, N+\mu_{k}} \mathbf{x}^{\prime}\right)$ and $\left(p_{-\left(N+m_{k}\right)-N} \mathbf{x}^{\prime \prime}, p_{N, N+m_{k}} \mathbf{x}^{\prime \prime}\right)$ belong to the same ball, then $d\left(p_{N} \Phi\left(\mathbf{x}^{\prime}\right)\right.$, $\left.p_{N} \Phi\left(\mathbf{x}^{\prime \prime}\right)\right) \leqslant d_{k}$. For $k$ large enough the number of elements of $T_{\kappa . / \prime}$ such that $\Phi\left(B_{l}^{N}\right) \cap C_{T_{k, x}}^{j}$ is nonempty is bounded by $C_{2}^{N}(T) C_{3}^{N} \exp R(\mathbf{x}, 1, N)$, where $C_{2}$ is a constant depending on the choice of the initial triangulation $T, C_{3}$ depends only on $\operatorname{dim} X$, and $\mathbf{x}$ is any point in $B_{I}^{N}$. For such a large $k$ we have

$$
\Gamma(k, N, \mathbf{x}) \leqslant e^{R(\mathbf{x} \cdot 1 \cdot N)} C_{2}^{N} C_{3}^{N} \alpha_{k}^{\prime \prime k}
$$

Making $N$ go to infinity gives

$$
h_{S . \infty}\left(T_{k}, \mu\right) \leqslant \ln C_{2}+\ln C_{3}+\int R(\mathbf{x}, 1) d \mu(\mathbf{x})
$$

and therefore

$$
h_{S, \infty}(\mu) \leqslant \ln C_{2}+\ln C_{3}+\int R(\mathbf{x}, 1) d \mu(\mathbf{x})
$$

Replacing $\Phi$ by $\Phi^{\prime \prime}$, we obtain

$$
m h_{S . \infty}(\mu) \leqslant \ln C_{2}+\ln _{3}+\int R(\mathbf{x}, m) d \mu(\mathbf{x})
$$

Dividing by $m$ and passing to the limit $m \rightarrow \infty$ provides the statement claimed.

## 6. SBR MEASURE

In ref. 5 a measure for $\Phi$ with the properties similar to those of the SBR measure in the finite-dimensional case was constructed under the assumption that $\Phi$ is a small perturbation of a system of noninteracting hyperbolic mappings.

Here we recall this construction. Let $\Lambda$ be a hyperbolic attractor for $f$ such that $\left.f\right|_{A}$ is topologically transitive. Then the tangent space at every point $x \in A$ can be decomposed into the sum $T_{x} X=E^{(u)}(x)+E^{(s)}(x)$, where

$$
\begin{array}{r}
\left.d f^{\prime \prime}\right|_{E^{(n)}(x)} \geqslant K_{3} \kappa_{3}^{\prime \prime} \\
\left.d f^{-n}\right|_{E^{(x)}(x)} \geqslant K_{3} \kappa_{3}^{\prime \prime} \tag{7}
\end{array}
$$

and the angle

$$
\begin{equation*}
\angle\left(E^{(\prime \prime)}(x), E^{(s)}(x)\right) \geqslant \gamma_{3} \tag{8}
\end{equation*}
$$

for some constants $K_{3}, \kappa_{3}>1$, and $\gamma_{3}$.
Consider a sequence of embeddings $I_{N}: X_{N} \rightarrow \mathbf{X}$ such that $\left\|I_{N}\right\|_{C^{\cdot 2}} \leqslant K_{4}$ and $P_{N} I_{N}=\mathrm{id}$ and let $\Phi_{N}=P_{N} \circ \Phi \circ I_{N}$ and $f_{N}=P_{N} \circ \mathbf{f} \circ I_{N}$ so that $\left(f_{N}\left(x^{(N)}\right)\right)_{i}=f\left(x_{i}^{(N)}\right)$. The following statements hold if $K_{1}$ and $\kappa_{1}$ are small enough and $J$ is close to identity in $C^{2}$-norm ${ }^{(5)}$ :
(1) $\Phi_{N}$ has an attractor $\Lambda_{N}$ on which $\Phi_{N}$ is conjugated to

$$
\left.f_{N}\right|_{\prod_{j=-N}^{v} A}
$$

and $\Phi$ has an attractor $\boldsymbol{\Lambda}$ on which $\Phi$ is conjugated to

$$
\left.\mathbf{f}\right|_{\Pi, A}
$$

In both cases the conjugation is close to identity;
(2) $\Phi_{N}$ is hyperbolic on $\Lambda_{N}$ and $\Phi$ is hyperbolic on $\boldsymbol{\Lambda}$. Moreover, the constants $K_{3}, \kappa_{3}$, and $\gamma_{3}$ can be chosen so that formulas (6)-(8) hold with $f$ replaced by $\Phi_{N}$ or $\Phi$.
(3) Let $\Pi_{f}$ be a Markov partition for $f, \Pi_{f_{n}}$ and $\Pi_{\mathrm{r}}$ be partitions whose elements are products of elements of $\Pi$ and $\Pi_{\mathscr{w}_{V}}$, and $\Pi_{\phi}$, be their images under the above-mentioned conjugations. $\Pi$ allows us to identify $\left.f\right|_{, A}$ with a subshift of the finite type $\left(\Sigma_{A}, \sigma\right)$ with an alphabet $\{1 \cdots l\}$, where $l=\operatorname{Card}(\Pi)$. Then $\Phi_{N}$ and $\Phi$ are semiconjugated to subshifts $\left(\Sigma_{A x}^{(N)}, \sigma\right)$ and $\left(\boldsymbol{\Sigma}_{A}, \sigma\right)$, respectively, with alphabets $\{1 \cdots l\}^{2 N+1}$ and $\{1 \cdots l\}^{2}$, respectively, and the transition matrices given by

$$
A_{N}\left(\vec{l}^{(1)}, \vec{l}^{(2)}\right)=\prod_{j=-, ~}^{N} A_{i,} i^{(1)} \cdot i^{(2)}, \quad \mathbf{A}\left(\vec{i}^{(1)}, \vec{i}^{(2)}\right)=\prod_{j \in K} A_{i}\left(j_{j}^{(1)} \cdot i_{j}^{(2)}\right.
$$

The mapping $S$ acts on $\Sigma$ as the space shift $S(\vec{i})_{k}^{j}=i_{k+1}^{j}$, where the superscript signifies the time coordinate and the subscript stands for the space coordinate. Let $\mu_{N}$ be the SBR measure on $\Lambda_{N}$ and $\hat{\mu}_{N}$ be its pullback to $\Sigma_{N}$. It is proven in ref. 5 that the $\left\{\mu_{N}\right\}$ converge to a measure $\mu$ on $\boldsymbol{\Lambda}$, that is, if $g: \mathbf{X} \rightarrow R$ is a function depending only on a finite number of coordinates, then

$$
\begin{equation*}
\int g d \mu_{n} \rightarrow \int g d \mu \tag{9}
\end{equation*}
$$

Moreover, if $\hat{\mu}$ is the pullback of $\mu$ on $\Sigma$ then the conditional expectations converge as well:

$$
\begin{aligned}
& \hat{\mu}_{N}\left(i_{0}^{0} \mid i_{-1}^{0} \cdots i_{-N}^{0}, i_{N}^{-1} \cdots i_{-N}^{-1} \cdots i_{k}^{-j} \cdots\right) \\
& \quad \rightarrow \hat{\mu}\left(i_{0}^{0} \mid i_{-1}^{0} \cdots i_{-L}^{0} \cdots \vec{l}^{-1} \vec{l}^{-2} \cdots \vec{l}^{-j} \cdots\right)
\end{aligned}
$$

The measure $\mu$ is mixing with respect to both $S$ and $\Phi$.
We now specify $I_{N}$ to be the periodic embedding $\left(I_{N}\left(x^{(N)}\right)\right)_{i}=x_{j}^{(N)}$, where $i \equiv j \bmod (2 N+1)$. The immediate corollary of the above-mentioned properties of $\lambda$ and $S$-invariance of $\lambda_{N}$ is the following statement.

Corollary 2. $h_{S . \phi}(\mu)=\lim _{N \rightarrow,}(1 / N) h_{\Phi_{N}}\left(\mu_{N}\right)$.

## 7. PESIN FORMULA

Let $\mu$ be SBR measure for $\Phi$. Since $\mu$ is both $S$ and $\Phi$-ergodic, $R(m)=$ $R(m, \mathbf{x})$ does not depend on $\mathbf{x}$. We write $R_{\mu}(\Phi)=\lim _{m \rightarrow \mu}[R(m) / m]$.

Theorem 4. $h_{S, \phi}(\mu)=R_{\mu}(\Phi)$.
Proof. We combine Corollary 2 with Pesin formula for $\Phi_{N}$ to get

$$
h_{S, \infty}(\mu)=\lim _{N \rightarrow \infty} \lim _{m \rightarrow \infty} \frac{1}{m N} \int R\left(d \Phi_{N}^{\prime \prime \prime}\right) d \mu_{N}\left(x^{(N)}\right)
$$

Our concern now is to show that the last two limits can be interchanged. Consider the decomposition

$$
T_{x^{(N)}} X_{N}=E_{N}^{(u)}\left(x^{(N)}\right)+E_{N}^{(s)}\left(x^{(N)}\right)
$$

and let a new metric $(\cdot, \cdot)^{\prime}$ on $T_{v^{\prime},{ }^{\prime},} X_{N}$ be given by the conditions $\|v\|_{2}^{\prime}=\|v\|_{2}$ for $v \in E_{N}^{(\mu)}\left(x^{(N)}\right)$ or $v \in E_{N}^{(*)}\left(x^{(N)}\right)$ and $E_{N^{\prime}}^{(\mu)} \perp^{\prime} E_{N}^{(s)}$. Since

$$
\frac{\|\cdot\|_{2}}{\sqrt{2}} \leqslant\|\cdot\|_{2}^{\prime} \leqslant \frac{\|\cdot\|_{2}}{\sqrt{1-\cos \gamma_{3}}}
$$

Corollary 1.4 implies

$$
\left|R\left(d \Phi_{N}^{\prime \prime \prime}\right)-\ln \operatorname{det}\left(d \Phi_{N}^{m} \mid E_{N}^{(u)}\left(x^{(N)}\right)\right)\right| \leqslant C_{4} N
$$

that is,

$$
\left\lvert\, \frac{1}{m N} R\left(d \Phi_{N}^{m}\right)-\frac{1}{m N} \ln \operatorname{det}\left(d \Phi_{N}^{m}\left|E_{N}^{(w)}\left(X^{N}\right)\right| \leqslant \frac{C_{4}}{m}\right.\right.
$$

But since

$$
\begin{aligned}
& \operatorname{det}\left(d \Phi_{N}^{m_{1}+m_{2}} \mid E_{N}^{(w)}\left(x^{(N)}\right)\right) \\
& \quad=\operatorname{det}\left(d \Phi_{N}^{m} \mid E_{N}^{(u)}\left(\Phi_{N}^{\left(m_{1}\right)}\left(x^{(N)}\right)\right)\right) \operatorname{det}\left(d \Phi_{N}^{m} \mid E_{N}^{(w)}\left(x^{(N)}\right)\right)
\end{aligned}
$$

the last inequality gives

$$
\left|\lim _{m \rightarrow \alpha} \frac{1}{m N} \int R\left(d \Phi_{N}^{m}\right) d \mu_{N}-\frac{1}{m_{0} N} \int R\left(d \Phi_{N}^{m_{0}}\right) d \mu_{N}\right| \leqslant \frac{C_{4}}{m_{0}}
$$

and hence

$$
h_{S, \phi}(\mu)=\lim _{m \rightarrow \infty} \lim _{N \rightarrow \infty} \frac{1}{m N} \int R\left(d \Phi_{N}^{\prime m}\left(x^{(N)}\right) d \mu_{N}\right.
$$

as claimed. Let us calculate the interior limit. By the same arguments as in the proof of Theorem 1 , given $\varepsilon$, we can find $L_{0}$ so large that for $L \geqslant L_{0}$

$$
\left|R\left(d \Phi_{N}^{\prime \prime \prime}\right)-\sum_{j=-N / L}^{N / L} R\left(d \Phi_{N}^{\prime \prime} \mid V^{j L+1 \cdot(j+1) L}\left(x^{(N)}\right)\right)\right| \leqslant \varepsilon N
$$

and, since $\mu_{N}$ is $S$-invariant,

$$
\left|\frac{1}{N} \int R\left(d \Phi_{N}^{m \prime}\right) d \mu_{N}\left(x^{(N)}\right)-\frac{1}{L} \int R\left(d \Phi_{N}^{\prime \prime \prime} \mid V^{L}\left(x^{(N)}\right)\right) d \mu_{N^{\prime}}\left(x^{(N)}\right)\right| \leqslant \varepsilon
$$

In other words,

$$
h_{\text {S. } w}(\mu)=\lim _{m \rightarrow \infty} \lim _{L \rightarrow \infty} \lim _{N \rightarrow \infty} \frac{1}{m L} \int R\left(d \Phi_{N}^{m} \mid V^{L}\left(x^{(N)}\right)\right) d \mu_{N}
$$

By the short-range conditions (1)-(2) there is $C_{5}=C_{5}(m, L)$ such that

$$
\left\|\left(d \Phi_{N}^{m}\left(x^{(N)}\right) \mid V^{L}\left(x^{(N)}\right)\right)-\left(d\left(\Phi^{\prime \prime \prime} \circ I_{N}\right)\left(x^{(N)}\right) \mid V^{L}\left(x^{(N)}\right)\right)\right\| \leqslant C_{s} \kappa_{1}^{N}
$$

Therefore

$$
h_{S, \neq N}(\mu)=\lim _{m \rightarrow \infty} \lim _{L \rightarrow \infty} \lim _{N \rightarrow \infty} \frac{1}{m L} \int R\left(d \Phi^{\prime \prime \prime} \mid V^{L}\left(I_{N} x^{(N)}\right)\right) d \mu_{N}\left(x^{(N)}\right)
$$

By construction of the measure $\mu$ [see formula (9)] the interior limit is equal to $\int R\left(d \Phi^{\prime \prime \prime} \mid V^{L}(\mathbf{x})\right) d \mu(\mathbf{x})$ and hence

$$
\begin{aligned}
h_{S: \Phi}(\mu) & =\lim _{m \rightarrow \infty} \lim _{l \rightarrow \infty} \frac{1}{m L} \int R\left(d \Phi^{m} \mid V^{L}(\mathbf{x})\right) d \mu(\mathbf{x}) \\
& =\lim _{m \rightarrow \infty} \frac{R(m)}{m}=R_{\mu}(\Phi) .
\end{aligned}
$$

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